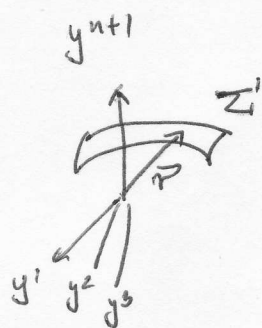


Hypersurfaces isometrically immersed in $\mathbb{R}^{n+1}$.

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$$g = dy^1{}^2 + dy^2{}^2 + \dots + (dy^{n+1})^2 = (d\vec{r})^2$$

$$d\vec{r} = (dy^1, dy^2, \dots, dy^{n+1})$$

$$\Sigma = \{ \vec{r} = (y^1, \dots, y^{n+1}) \in \mathbb{R}^{n+1} : \vec{r} = \vec{r}(x^1, \dots, x^n) \}$$

$$dx^1 \dots dx^n \neq 0 \quad ?$$

$$g|_{\Sigma} = |d\vec{r}(x^1, \dots, x^n)|^2 = \tilde{g}_{\mu\nu} dx^{\mu} dx^{\nu} = g_{\mu\nu} \theta^{\mu} \theta^{\nu} = \underbrace{\theta^1{}^2 + \dots + \theta^n{}^2}_{\text{orthonormal frame}}$$

$$g_{\mu\nu} = \delta_{\mu\nu} \quad \text{orthonormal frame}$$

$(\theta^1, \dots, \theta^n)$ orthonormal frame on Σ

$(e_1, \dots, e_n)$ dual frame on Σ ,

We tautologically have:

$$(2) \quad \boxed{d\vec{r} = e_1(\vec{r})\theta^1 + e_2(\vec{r})\theta^2 + \dots + e_n(\vec{r})\theta^n} \quad (\text{e.g. } e_3 d\vec{r} = e_3(\vec{r}))$$

and let us denote $e_{\mu}(\vec{r})$ by $\vec{e}_{\mu}$:

$$\boxed{\vec{e}_{\mu} = e_{\mu}(\vec{r})} \quad \text{— Vectors in } \mathbb{R}^{n+1} \quad !!!$$

Fact

$$\boxed{\vec{e}_{\mu} \cdot \vec{e}_{\nu} = \delta_{\mu\nu}} \quad (1)$$

Proof

$$\theta^1{}^2 + \dots + \theta^n{}^2 = \underbrace{\delta_{\mu\nu} \theta^{\mu} \theta^{\nu}}_{(d\vec{r})^2} = (\vec{e}_{\mu} \theta^{\mu}) \cdot (\vec{e}_{\nu} \theta^{\nu}) = \underbrace{(\vec{e}_{\mu} \cdot \vec{e}_{\nu})}_{\delta_{\mu\nu}} \theta^{\mu} \theta^{\nu}$$

□.

Let $\vec{n} \in \mathbb{R}^{n+1}$ s.t. $\forall (x^1, \dots, x^n) = \vec{r} \quad \vec{n} \cdot \vec{e}_{\mu} = 0$ and $\vec{n}^2 = 1$.

Thus

$(\vec{e}_{\mu}, \vec{n})$ is an orthonormal basis in $\mathbb{R}^{n+1}$ at each point of Σ .

Cartan's lemma

Let $A_{\mu\nu}$, $\mu, \nu = 1, \dots, n$ be 1-forms on n -dimensional manifold M s.t.
 $A_{\mu\nu} = -A_{\nu\mu}$, Let θ^μ be a coframe on M .

If $A_{\mu\nu} \wedge \theta^\nu = 0$ then $A_{\mu\nu} = 0$.

Proof

$$0 = A_{\mu\nu} \wedge \theta^\nu = A_{\mu\nu} \theta^\mu \wedge \theta^\nu = 0 \Rightarrow A_{\mu[\nu} \theta^\mu \wedge \theta^\nu] = 0 \Rightarrow$$

$$\begin{cases} \cancel{A_{\mu\nu}} \theta^\mu - A_{\mu\nu} \theta^\nu = 0 \\ A_{\mu\nu} \theta^\mu - \cancel{A_{\nu\mu}} \theta^\nu = 0 \\ \cancel{A_{\nu\mu}} \theta^\nu - A_{\mu\nu} \theta^\mu = 0 \end{cases} \Leftrightarrow \text{but; } A_{\mu\nu} = -A_{\nu\mu}$$

$$2A_{\mu\nu} \theta^\nu = 0 \Rightarrow A_{\mu\nu} \theta^\nu = A_{\mu\nu} = 0. \quad \square$$

How the Levi-Civita connection $\Gamma_{\mu\nu}^\lambda$ of the induced metric $g = \delta_{\mu\nu} \theta^\mu \theta^\nu$ look like?

Calculate $d\vec{e}_\mu$:

$$\boxed{d\vec{e}_\mu = b_\mu \vec{n} + \gamma_{\mu\nu} \vec{e}_\nu}$$

This defines 1-forms b_μ and $\gamma_{\mu\nu}$ on Σ .

Obviously

$$\begin{cases} b_\mu = d\vec{e}_\mu \cdot \vec{n} \\ \gamma_{\mu\nu} = d\vec{e}_\mu \cdot \vec{e}_\nu \end{cases} \text{ and are totally determined by specifying } \vec{r} = \vec{r}(x^A) \text{ defining } \Sigma.$$

Fact

$$\gamma_{\mu\nu} = -\gamma_{\nu\mu}.$$

Proof

$$\delta_{\mu\nu} = \vec{e}_\mu \cdot \vec{e}_\nu \Rightarrow 0 = d\vec{e}_\mu \cdot \vec{e}_\nu + \vec{e}_\mu \cdot d\vec{e}_\nu = \gamma_{\mu\nu} + \gamma_{\nu\mu}. \quad \square$$

Of course $d\theta^\mu$ is decomposable onto $\theta^\mu \wedge \theta^\nu$ and one can look for $\Gamma_{\mu\nu}$ st $d\theta^\mu + \Gamma^\mu_{\nu} \wedge \theta^\nu = 0$, $\Gamma_{\mu\nu} = \delta_{\mu\nu} \Gamma^\mu_\nu$, $\Gamma_{\mu\nu} + \Gamma_{\nu\mu} = 0$.

We have:

Proposition

$$1) \quad \Gamma_{\mu\nu} = \gamma_{\mu\nu} = d\vec{e}_\mu \cdot \vec{e}_\nu$$

$$2) \quad b_{\mu\nu} = b_{\nu\mu} \text{ where } b_\mu = d\vec{e}_\mu \cdot \vec{n} = b_{\mu\nu} \theta^\nu.$$

Proof

We use (2) on Σ^1 :

$$\begin{aligned} 0 &= d^2 \vec{r} = d(\vec{e}_\mu \theta^\mu) = d\vec{e}_\mu \wedge \theta^\mu + \vec{e}_\mu d\theta^\mu \stackrel{\downarrow}{=} \\ &= d\vec{e}_\mu \wedge \theta^\mu - \vec{e}_\mu \Gamma^\mu_{\nu} \wedge \theta^\nu = (b_\mu \vec{n} + \gamma_{\mu\nu} \vec{e}_\nu) \wedge \theta^\mu - \vec{e}_\nu \Gamma^\nu_{\mu} \wedge \theta^\mu = \\ &= b_\mu \wedge \theta^\mu \vec{n} + (\gamma_{\mu\nu} - \Gamma^\nu_{\mu}) \wedge \theta^\mu \vec{e}_\nu = \\ &= b_\mu \wedge \theta^\mu \cdot \vec{n} + (\gamma_{\mu\nu} - \Gamma_{\nu\mu}) \wedge \theta^\mu \vec{e}_\nu \end{aligned}$$

$$\Rightarrow \begin{cases} b_\mu \wedge \theta^\mu = 0 \\ (\gamma_{\mu\nu} - \Gamma_{\nu\mu}) \wedge \theta^\mu = 0 \end{cases} \Rightarrow b_{\mu\nu} \theta^\nu \wedge \theta^\mu = 0 \Rightarrow b_{[\mu\nu]} = 0$$

antisymmetric + Cartan's lemma

$$\Rightarrow \Gamma_{\nu\mu} = \gamma_{\nu\mu}$$

$\Downarrow$
 $b_{\mu\nu}$ is symmetric.

□.

Def

Form $b = b_{\mu\nu} \theta^\mu \theta^\nu$ where $b_\mu = d\vec{e}_\mu \cdot \vec{n} = b_{\mu\nu} \theta^\nu$ is called 2nd fundamental form for Σ .

We have

$$\boxed{d\vec{e}_\mu = b_\mu \vec{n} + \Gamma_{r\mu} \vec{e}_r} \quad (3)$$

where $\Gamma_{r\mu} = d\vec{e}_\mu \cdot \vec{e}_r$ are the Levi-Civita connection 1-forms for $g_{I2} = \delta_\mu \delta^\mu \theta^\mu$.

Proposition

$$\boxed{d\vec{n} = -b_\mu \vec{e}_\mu} \quad (4)$$

Proof

$$\vec{n}^2 = 1 \Rightarrow d\vec{n} \cdot \vec{n} = 0$$

$$\vec{e}_\mu \cdot \vec{n} = 0 \Rightarrow d\vec{e}_\mu \cdot \vec{n} = -\vec{e}_\mu \cdot d\vec{n}$$

$$\begin{matrix} \parallel \\ b_\mu \end{matrix} \quad (**)$$

$$\Rightarrow d\vec{n} = \alpha \vec{n} + \beta_\mu \vec{e}_\mu \quad \text{and} \quad \alpha = 0$$

$$(**) \quad \beta_\mu = -b_\mu$$

□.

Compatibility conditions for

$$\begin{cases} d\vec{e}_\mu = b_\mu \vec{n} + \Gamma_{r\mu} \vec{e}_r \\ d\vec{n} = -b_\mu \vec{e}_\mu \end{cases}$$

$$\begin{aligned}
 d^2 \vec{e}_\mu = 0 &= \underline{db_\mu \vec{n}} + \cancel{b_\mu \wedge b_\nu \vec{e}_\nu} + \cancel{d\Gamma_{\nu\mu} \vec{e}_\nu} - \Gamma_{\nu\mu} \wedge (\underline{b_\nu \vec{n}} + \cancel{\Gamma_{\nu\mu} \vec{e}_\nu}) \\
 &= (db_\mu + b_\nu \wedge \Gamma_{\nu\mu}) \vec{n} + (d\Gamma_{\nu\mu} - \Gamma_{\nu\mu} \wedge \Gamma_{\nu\mu} + b_\mu \wedge b_\nu) \vec{e}_\nu
 \end{aligned}$$

$$\Rightarrow \boxed{
 \begin{aligned}
 db_\mu + b_\nu \wedge \Gamma_{\nu\mu} &= 0 && \leftarrow \text{Codazzi} \\
 \Omega_{\nu\mu} &= b_\nu \wedge b_\mu && \leftarrow \text{Gauss}
 \end{aligned}
 }$$

The second compatibility conditions:

$$\begin{aligned}
 d^2 \vec{n} = 0 &= -db_\mu \vec{e}_\mu + b_\mu \wedge (b_\mu \vec{n} + \Gamma_{\nu\mu} \vec{e}_\nu) = \\
 &= (-db_\mu + b_\nu \wedge \Gamma_{\nu\mu}) \vec{e}_\mu + b_\mu \wedge b_\mu \vec{n} \quad \text{satisfied iff} \\
 &\quad \text{G-Codazzi satisfied.}
 \end{aligned}$$

Thm

Let (M, g) be an n -dimensional Riemannian manifold.

Let b be a bilinear symmetric form on M and let (θ^a) be an orthonormal coframe for g , $g = \delta_{\mu\nu} \theta^\mu \theta^\nu$.

Then b can be a second fundamental form for an isometric immersion of g in $\mathbb{R}^{n+1}$ with the standard euclidean metric provided that

$$(G-C) \quad \begin{cases} db_\mu + b_\nu \wedge \Gamma_{\nu\mu} = 0 \\ \Omega_{\nu\mu} = b_\nu \wedge b_\mu \end{cases}$$

where $\Gamma_{\mu\nu}$ and $\Omega_{\nu\mu}$ are respective (L.C.) connection 1-forms and curvature 2-forms in coframe (θ^a) and b_ν is defined by $b = b_{\mu\nu} \theta^\mu \theta^\nu$, $b_\nu = b_{\nu\mu} \theta^\mu$.

Rem. If $n=2$ conditions (G-C) are also sufficient.

If the Gauss-Codazzi equations are satisfied the equations to be solved to get the isometric immersion are:

$$\begin{cases} d\vec{e}_\mu = b_\mu \vec{n} + \Gamma_{\nu\mu} \vec{e}_\nu \\ d\vec{n} = -b_\mu \vec{e}_\mu \end{cases}$$

Example

Take $\boxed{g = dx^2 + 2\cos\omega dx dy + dy^2}$, (M) $\omega = \omega(x, y)$

Curvature:

$$g = (dx + \cos\omega dy)^2 - \cos^2\omega dy^2 + dy^2 = (dx + \cos\omega dy)^2 + \sin^2\omega dy^2$$

$$\begin{cases} \theta^1 = dx + \cos\omega dy \\ \theta^2 = \sin\omega dy \end{cases} \quad g = \theta^1{}^2 + \theta^2{}^2$$

$$\boxed{\begin{aligned} d\theta^1 &= -\omega_x \sin\omega dx dy = -\omega_x dx \theta^2 = -\omega_x \theta^1 \theta^2 \\ d\theta^2 &= \omega_x \cos\omega dx dy = \omega_x \cos\omega \theta^1 \frac{1}{\sin\omega} \theta^2 = \omega_x \cot\omega \theta^1 \theta^2 \end{aligned}}$$

$$d\theta^1 = -\Gamma_{12}^1 \theta^2 = -\Gamma_{12}^2 \theta^2 = -\omega_x \theta^1 \theta^2$$

$$\Rightarrow \Gamma_{12} = \omega_x \theta^1 + \alpha \theta^2$$

$$d\theta^2 = -\Gamma_{12}^2 \theta^1 = \Gamma_{12}^1 \theta^2 = \alpha \theta^2 \theta^1 = \omega_x \cot\omega \theta^1 \theta^2$$

$$\Rightarrow \boxed{\Gamma_{12} = \omega_x (\theta^1 - \cot\omega \theta^2)} = \omega_x dx$$

$$R_{12} = d\Gamma_{12} + 0 = d(\omega_x dx) = \omega_{xy} dy dx = -\frac{\omega_{xy}}{\sin\omega} \theta^1 \theta^2$$

Proposition

Metric (M) has curvature K if

$$\boxed{\omega_{xy} = -K \sin\omega}$$

$$K = K(x, y).$$

In particular: (M) has scalar curvature equal to

$$\boxed{K = -1} \text{ ASSUMED FROM NOW, ON}$$

iff function ω satisfies 'sine-Gordon' equation!

$$\boxed{\omega_{xy} = \sin \omega}$$

When g as in (M) can be isometrically immersed in $\mathbb{R}^3$

with $b = 2b_{xy} dx dy$ being the second fundamental form?

$$b = 2b_{xy} (\theta' - \cot \omega \theta^2) \frac{1}{\sin \omega} \theta^2$$

$$b_1 = \frac{b_{xy}}{\sin \omega} \theta^2$$

$$b_2 = \frac{b_{xy}}{\sin \omega} \theta^4 - 2 \frac{b_{xy}}{\sin \omega} \cot \omega \theta^2$$

Gauss equation:

$$-\theta' \wedge \theta^2 = \Omega_{12} = b_1 \wedge b_2 = - \frac{b_{xy}^2}{\sin^2 \omega} \theta' \wedge \theta^2$$

$$\Rightarrow \boxed{b_{xy} = \sin \omega}$$

$$\text{Thus } \boxed{b = 2 \sin \omega dx dy}$$

Godazzi equations: $b_1 = \theta^2, \quad b_2 = \theta' - 2 \cot \omega \theta^2$

$$db_1 = \omega_x \cot \omega \theta' \theta^2$$

$$\text{C.E. 1} \quad \begin{matrix} \parallel \\ -b_2 \wedge \Gamma_{21} = b_2 \Gamma_{12} \end{matrix} = (\theta' - 2 \cot \omega \theta^2) \omega_x (\theta' - \cot \omega \theta^2) = -\omega_x \cot \omega \theta^2 \theta' \quad \checkmark$$

C.E. 2 8

$$dl_2 = -\omega_x \theta'^2 + 2 \frac{\omega_x}{\sin^2 \omega} \theta' \theta'' - 2 \cot^2 \omega \omega_x \theta'^2 =$$

$$= \omega_x \frac{-\sin^2 \omega + 2 - 2 \cos^2 \omega}{\sin^2 \omega} \theta' \theta'' = \omega_x \theta' \theta''$$

$$-b_1 \Gamma_{12} = -\theta'^2 \omega_x \theta' \quad \checkmark$$

Thus if

$$\left[\begin{array}{l} g = dx^2 + 2 \cos \omega dx dy + dy^2 \\ b = 2 \sin \omega dx dy \end{array} \right. \quad \omega_{xy} = \sin \omega$$

then g can be isometrically immersed in $\mathbb{R}^3$ with b being the $\mathbb{I}^{nd}$ fundamental form.

Examples of solutions to

$$\begin{cases} d\vec{e}_\mu = b_\mu \vec{n} + \Gamma_{\mu\nu} \vec{e}_\nu \\ d\vec{n} = -b_\mu \vec{e}_\mu \end{cases}$$

Homework

Show that the surface in $\mathbb{R}^3$

$$z = -\sqrt{1-x^2-y^2} + \log \frac{1+\sqrt{1-x^2-y^2}}{\sqrt{x^2+y^2}}$$

~~the~~ correspond to a solution of the sine-gordon equation

$$\omega_{xy} = \sin \omega,$$

written in coordinates $x = \frac{\tau + \xi}{\sqrt{2}}, y = \frac{\tau - \xi}{\sqrt{2}},$

~~not~~ not depending on ξ , and vanishing when $\tau \rightarrow \infty$.

Immersing n -dimensional manifolds in $\mathbb{R}^{n+k}$.

$$g = dy^1{}^2 + \dots + dy^{n+k}{}^2 = (d\vec{r})^2$$

$$\Sigma_n = \{ \vec{r} = (y^1, \dots, y^{n+k}) \in \mathbb{R}^{n+k}, \quad \vec{r} = \vec{r}(x^1, \dots, x^n) \\ dx^1 \wedge \dots \wedge dx^n \neq 0 \}.$$

$$g|_{\Sigma} = |d\vec{r}|^2 = \tilde{g}_{\mu\nu} dx^\mu dx^\nu = \delta_{\mu\nu} \theta^\mu \theta^\nu = \theta^1{}^2 + \dots + \theta^n{}^2$$

$\{\theta^\mu\}$ orthonormal coframe, $\mu=1, \dots, n$

$\{e_\mu\}$ dual frame

$$d\vec{r} = e_\mu(\vec{r}) \theta^\mu$$

$$e_\mu(\vec{r}) = \vec{e}_\mu$$

$\vec{e}_\mu \cdot \vec{e}_\nu = \delta_{\mu\nu}$ - orthonormal vectors in $\mathbb{R}^{n+k}$

Let $(\vec{n}_a)$ $a=1, \dots, k$ be vectors in $\mathbb{R}^{n+k}$ which are

- normal to Σ at each point of Σ $\vec{n}_a \cdot \vec{e}_\mu = 0$
- orthogonal to each other $\vec{n}_a \cdot \vec{n}_b = 0$ $a \neq b$
- unitary $\vec{n}_a^2 = 1 \quad \forall a=1, \dots, k$ $\vec{n}_a \cdot \vec{n}_b = \delta_{ab}$

$(\vec{e}_\mu, \vec{n}_a)$ is orthonormal basis in $\mathbb{R}^{n+k}$ attached to each point of Σ .

$$\begin{cases} d\vec{e}_\mu = b_{\mu a} \vec{n}_a + \gamma_{\nu\mu} \vec{e}_\nu \\ d\vec{n}_a = \alpha_{ab} \vec{n}_b + \beta_{\mu a} \vec{e}_\mu \end{cases}$$

$$\Rightarrow \begin{cases} \gamma_{r\mu} = d\vec{e}_\mu \cdot \vec{e}_r \\ b_{\mu a} = d\vec{e}_\mu \cdot \vec{n}_a \\ \alpha_{ab} = d\vec{n}_a \cdot \vec{n}_b \\ \beta_{\mu a} = d\vec{n}_a \cdot \vec{e}_\mu \end{cases}$$

$$0 = d(\vec{e}_\mu \cdot \vec{e}_r) = \gamma_{r\mu} + \gamma_{\mu r} \Rightarrow \gamma_{\mu r} = -\gamma_{r\mu}$$

$$\begin{aligned} 0 = d^2 \vec{r} &= d\vec{e}_\mu \theta^\mu + \vec{e}_\mu d\theta^\mu = \\ &= (b_{\mu a} \vec{n}_a + \gamma_{\mu r} \vec{e}_r) \theta^\mu + \vec{e}_\mu (-\Gamma_{\mu\sigma} \theta^\sigma) = \\ &= b_{\mu a} \theta^\mu \vec{n}_a + (\gamma_{\mu r} - \Gamma_{\mu r}) \theta^\mu \vec{e}_r \end{aligned}$$

$$\Rightarrow b_{\mu a} \theta^\mu = 0 \quad \text{and} \quad \boxed{\gamma_{\mu r} = \Gamma_{r\mu}} \quad \text{Cartan's lemma,}$$

$$b_{\mu\sigma a} \theta^\sigma \theta^\mu = 0$$

$$\Rightarrow \boxed{b_{\mu\sigma a} = b_{\sigma\mu a}}$$

$$b_{\mu a} = b_{\mu\sigma a} \theta^\sigma$$

$$\boxed{b_a = b_{\mu\sigma a} \theta^\mu \theta^\sigma} \leftarrow \text{second fundamental form along } \vec{n}_a.$$

$$\boxed{d\vec{e}_\mu = b_{\mu a} \vec{n}_a + \Gamma_{\mu r} \vec{e}_r}$$

$$b_{\mu a} \rightsquigarrow b_a \uparrow \text{second fundamental form.}$$

$$\vec{n}_a \cdot \vec{n}_b = \delta_{ab} \Rightarrow d\vec{n}_a \cdot \vec{n}_b + \vec{n}_a \cdot d\vec{n}_b = 0$$

$$\boxed{\alpha_{ab} = -\alpha_{ba}}$$

$$0 = d(\vec{n}_a \cdot \vec{e}_\mu) = d\vec{n}_a \cdot \vec{e}_\mu + \vec{n}_a \cdot d\vec{e}_\mu = b_{\mu a} + d\vec{n}_a \cdot \vec{e}_\mu = b_{\mu a} + \beta_{\mu a}$$

$$\beta_{\mu a} = -b_{\mu a}$$

$\Rightarrow$

$$\begin{cases} d\vec{e}_\mu = b_{\mu a} \vec{n}_a + \Gamma_{r\mu} \vec{e}_r \\ d\vec{n}_a = \alpha_{ab} \vec{n}_b - b_{\mu a} \vec{e}_\mu \end{cases}$$

$$\begin{cases} b_{\mu a} = d\vec{e}_\mu \cdot \vec{n}_a \\ \alpha_{ab} = d\vec{n}_a \cdot \vec{n}_b \end{cases}$$

$$\alpha_{ab} = -\alpha_{ba}$$

$$b_{\mu\nu a} = b_{\nu\mu a} \text{ where } b_{\mu a} = b_{\nu a} \theta^\nu$$

Compatibility:

$$\begin{aligned} 0 &= \underline{db_{\mu a} \vec{n}_a} + b_{\mu a} (\alpha_{ab} \vec{n}_b - b_{\mu a} \vec{e}_\mu) + \\ &\quad + d\Gamma_{r\mu} \vec{e}_r - \Gamma_{r\mu} (b_{ra} \vec{n}_a + \Gamma_{rs} \vec{e}_s) = \\ &= (db_{\mu a} - b_{\mu b} \alpha_{ba} + b_{ra} \Gamma_{r\mu}) \vec{n}_a + \\ &\quad + (d\Gamma_{r\mu} - \Gamma_{rs} \Gamma_{r\mu} + b_{\mu a} b_{ra}) \vec{e}_r \end{aligned}$$

$$\Rightarrow \left\{ \begin{array}{l} db_{\mu a} + b_{ra} \Gamma_{r\mu} - b_{\mu b} \alpha_{ba} = 0 \quad \leftarrow \text{Codazzi} \\ \Omega_{r\mu} = b_{ra} \wedge b_{\mu a} \quad \quad \quad \leftarrow \text{Gauss} \end{array} \right.$$

$$\begin{aligned} 0 &= \underline{d\alpha_{ab} \vec{n}_b} + \alpha_{ab} d\vec{n}_b - db_{\mu a} \vec{e}_\mu + b_{\mu a} d\vec{e}_\mu = \\ &= d\alpha_{ab} \vec{n}_b - \alpha_{ab} (\alpha_{bc} \vec{n}_c - b_{\mu b} \vec{e}_\mu) + \\ &\quad + (b_{ra} \Gamma_{r\mu} - b_{\mu b} \alpha_{ba}) \vec{e}_\mu - b_{\mu a} (b_{\mu b} \vec{n}_b + \Gamma_{r\mu} \vec{e}_r) \end{aligned}$$

$$d\alpha_{ab} - \alpha_{ac} \wedge \alpha_{cb} - b_{\mu a} \wedge b_{\mu b} = 0$$

$$\cancel{\alpha_{ab} b_{\mu b}} + \cancel{b_{ra} \Gamma_{r\mu}} - \cancel{b_{\mu b} \alpha_{ba}} - \cancel{b_{ra} \Gamma_{\mu r}} = 0$$

$$\Rightarrow \left[\begin{array}{l} \Omega_{\nu\mu} = b_{ra} \wedge b_{\mu a} \\ db_{\mu a} + b_{ra} \wedge \Gamma_{r\mu} - b_{\mu b} \wedge \alpha_{ba} = 0 \\ d\alpha_{ab} - \alpha_{ac} \wedge \alpha_{cb} = b_{\mu a} \wedge b_{\mu b} \end{array} \right. \begin{array}{l} \leftarrow \text{Gauss} \\ \leftarrow \text{Codazzi} \\ \leftarrow \text{Ricci} \end{array}$$

α_{ab} are (sometimes) called torsions

Thm Schläfli (Cartan).

Any analytic Riemannian manifold of dimension n can be locally isometrically embedded in a Riemannian ~~man~~ flat manifold of dimension $N \leq \frac{n(n+1)}{2}$

If flat is replaced by Ricci flat then $N \leq n+1$

(Campbell 1926)

A course of differential geometry
(Clarendon Press Oxford)